

VAriable Speed COntroller

Operating manual

VASCO





Index

| 1. VASCO Introduction | 3 |
|--|----|
| 2. Safety Instructions | 3 |
| 3. Technical Characteristics | 4 |
| 3.1 Weight and dimensions | 5 |
| 4. Electric wiring | 6 |
| 4.1 Protections | 12 |
| 4.2 Electromagnetic compliance | 12 |
| 4.3 Installation with long motor cables | 12 |
| 5. VASCO installation | 13 |
| 5.1 VASCO Installation for constant pressure control | 16 |
| 5.1.1 Pressure tank | 16 |
| 5.1.2 Pressure sensor | 16 |
| 5.2 VASCO installation for differential constant pressure applications | 17 |
| 5.2.1 Sensors wiring | 17 |
| 5.2.2 Programming | 17 |
| 6. VASCO Use and Programming | 18 |
| 6.1 VASCO display | 18 |
| 6.2 Initial configuration | 18 |
| 6.3 Initial view | 20 |
| 6.4 Menu view | 21 |
| 6.5 Control parameters | 21 |
| 6.6 Motor parameters | 25 |
| 6.7 IN/OUT parameters | 27 |
| 6.8 Connectivity parameters | 28 |
| 7. Protections and alarms | 29 |
| 8. Auxiliary pumps during constant pressure control | 31 |
| 8.1 DOL pumps | 32 |
| 8.2 COMBO function | 33 |
| 9. Trouble-shooting chart | 36 |
| 10 Technical Assistance | 27 |

1. VASCO Introduction

VASCO is a variable frequency drive designed to control and protect pumping systems by varying the output frequency to the pump.

VASCO can be applied to both new and existing pumping systems, and provides:

- energy and cost savings
- simplified installation and an overall lower pumping system cost
- longer life of the pumping system and relevant components
- improved reliability

VASCO, when connected to any pump, manages the system operation to maintain a certain constant physical quantity (pressure, differential pressure, flow, temperature, etc.) regardless of the conditions of use. The pump is operated only when needed thus avoiding unnecessary energy consumption.

VASCO at the same time is able to:

- protect the motor from overload and dry running
- implement soft start and soft stop to increase the system life and reduce current peaks
- provide an indication of current consumption, voltage, and power
- maintain a record of run time and display any errors and/or failures reported by the system
- control up to two additional pumps at a constant speed (Direct On Line)
- connect to other VASCO units for combined operation

Through the use of inductive filters (optional) VASCO eliminates dangerous surges that are induced in long cables, making VASCO suitable for control of submersible pumps.

2. Safety Instructions

The manufacturer strongly suggests carefully reading this operation manual before using and installing its products Any operation (installation, maintenance and repair) must be carried out by trained, skilled, and qualified personnel. Failure to observe and follow the instructions in this manual may result in dangerous and potentially lethal electric shock. Pay attention to all standard safety and accident prevention regulations



The device must be connected to main power supply via a switch to ensure the complete disconnection from the network before any operation on the VASCO itself (including visual inspection) and/or on the connected load.

Disconnect VASCO from the main power supply before commencing any work.



Do not remove, for any reason, the cover and the cable plate without having first disconnected the device from the main power supply and having waited at least 5 minutes.

VASCO and pumping system must be grounded properly before operation. For the entire period VASCO is powered, high voltage is present on the output terminals of the inverter whether or not the pump is running.

Tightening all screws on the cover with washers is recommended before powering the device. Otherwise, there may be a failure to connect the cover to ground, creating the risk of electric shock or even death.

Avoid any shock or significant impact during transport.

Check the VASCO immediately upon delivery and check for damage and/or missing parts. If either occurs, immediately notify the supplier.

Damages due to transport, incorrect installation, or improper use of the device will null and void the warranty.

Tampering or disassembly of any component will automatically void the warranty.

The manufacturer cannot be held responsible for any damages to people and/or property due to improper use of its products.

3. Technical Characteristics

| Model | Vin +/- 15% [V] | Max V out [V] | Max I in [A] | Max I out [A] | P2 motor power* [kW] | Size |
|-----------|-----------------|------------------|-----------------|------------------|----------------------------|------|
| VASCO 209 | 1 x 230 | 1 x Vin | 15 | 9 | 1,1 | 1 |
| VA3CO 209 | 1 X 230 | 3 x Vin | | 7 | 1,5 | 1 |
| VASCO 214 | 1 x 230 | 1 x Vin | 20 | 9 | 1,1 | 1 |
| VA300 214 | 1 X 230 | 3 x Vin | | 11 | 3 | 1 |
| VASCO 218 | 1 x 230 | 3 x Vin | 38 | 18 | 4 | 2 |
| VASCO 225 | 1 x 230 | 3 x Vin | 53 | 25 | 5,5 | 2 |
| VASCO 306 | 3 x 230 | 3 x Vin | 10 | 6 | 1,1 | 1 |
| VASCO 309 | 3 x 230 | 3 x Vin | 13,5 | 9 | 2,2 | 1 |
| VASCO 314 | 3 x 230 | 3 x Vin | 16 | 14 | 3 | 2 |
| VASCO 318 | 3 x 230 | 3 x Vin | 21 | 18 | 4 | 2 |
| VASCO 325 | 3 x 230 | 3 x Vin | 31 | 25 | 5,5 | 2 |
| VASCO 330 | 3 x 230 | 3 x Vin | 35 | 30 | 7,5 | 2 |
| VASCO 338 | 3 x 230 | 3 x Vin | 42 | 38 | 9,2 | 3 |
| VASCO 348 | 3 x 230 | 3 x Vin | 52 | 48 | 11 | 3 |
| VASCO 365 | 3 x 230 | 3 x Vin | 68 | 65 | 15 | 3 |
| VASCO 375 | 3 x 230 | 3 x Vin | 78 | 75 | 18,5 | 3 |
| VASCO 385 | 3 x 230 | 3 x Vin | 88 | 85 | 22 | 3 |
| VASCO 406 | 3 x 380 - 460 | 3 x Vin | 10 | 6 | 2,2 | 1 |
| VASCO 409 | 3 x 380 - 460 | 3 x Vin | 13,5 | 9 | 4 | 1 |
| VASCO 414 | 3 x 380 - 460 | 3 x Vin | 16 | 14 | 5,5 | 2 |
| VASCO 418 | 3 x 380 - 460 | 3 x Vin | 21 | 18 | 7,5 | 2 |
| VASCO 425 | 3 x 380 - 460 | 3 x Vin | 31 | 25 | 11 | 2 |
| VASCO 430 | 3 x 380 - 460 | 3 x Vin | 35 | 30 | 15 | 2 |
| VASCO 438 | 3 x 380 - 460 | 3 x Vin | 42 | 38 | 18,5 | 3 |
| VASCO 448 | 3 x 380 - 460 | 3 x Vin | 52 | 48 | 22 | 3 |
| VASCO 465 | 3 x 380 - 460 | 3 x Vin | 68 | 65 | 30 | 3 |
| VASCO 475 | 3 x 380 - 460 | 3 x Vin | 78 | 75 | 37 | 3 |
| VASCO 485 | 3 x 380 - 460 | 3 x Vin | 88 | 85 | 45 | 3 |

Power frequency: 50 - 60 Hz (+/- 2%)

Max. ambient temperature at nominal current: 40°C (104 °F)

Max. altitude at nominal current: 1000 m

Grade of protection: IP55 (SIZE 1,2), IP54 (SIZE 3) *

RS485 serial communication

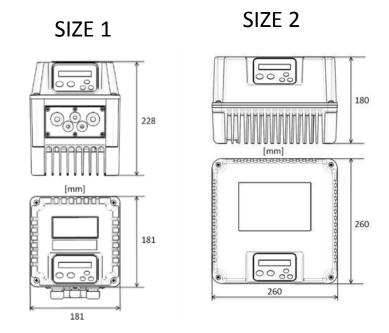
VASCO is able to power the motor with a higher current for a short period of time according to the linear relation: 101% of the nominal current for 10min., 110% nominal current for 1 min.

 $^{^*\} auxiliary\ cooling\ fan\ of\ the\ VASCO,\ used\ in\ wall\ mounted\ applications,\ has\ a\ protection\ rating\ of\ IP54.$

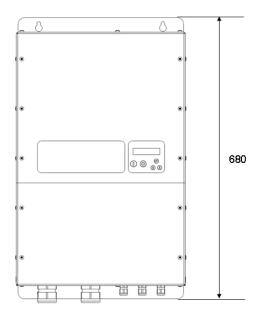
3.1 Weight and dimensions

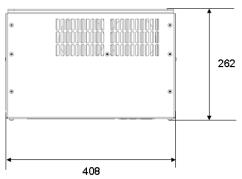
| Model | Weight * | Size |
|-----------|----------|------|
| iviodei | | |
| | [Kg] | |
| VASCO 209 | 4 | 1 |
| VASCO 214 | 4,3 | 1 |
| VASCO 218 | 7,2 | 2 |
| VASCO 225 | 7,2 | 2 |
| VASCO 306 | 4,4 | 1 |
| VASCO 309 | 4,4 | 1 |
| VASCO 314 | 7 | 2 |
| VASCO 318 | 7 | 2 |
| VASCO 325 | 7 | 2 |
| VASCO 330 | 7,2 | 2 |
| VASCO 338 | 33 | 3 |
| VASCO 348 | 33 | 3 |
| VASCO 465 | 34 | 3 |
| VASCO 375 | 34 | 3 |
| VASCO 385 | 34 | 3 |
| VASCO 406 | 4,4 | 1 |
| VASCO 409 | 4,4 | 1 |
| VASCO 414 | 7 | 2 |
| VASCO 418 | 7 | 2 |
| VASCO 425 | 7 | 2 |
| VASCO 430 | 7,2 | 2 |
| VASCO 438 | 33 | 3 |
| VASCO 448 | 33 | 3 |
| VASCO 465 | 34 | 3 |
| VASCO 475 | 34 | 3 |
| VASCO 485 | 34 | 3 |

^{*} Weight without packing.



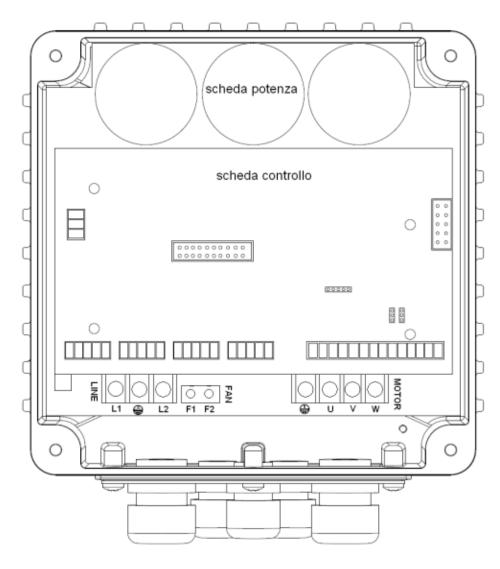
SIZE 3





4. Electric wiring

Power board VASCO 209,214



Power supply:

LINE: L1, L2,GND

It is recommended to use cable lugs

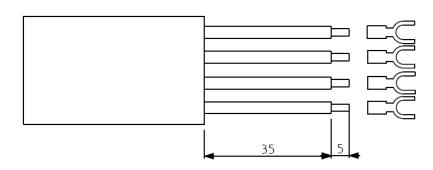
Output:

3 ph motor:

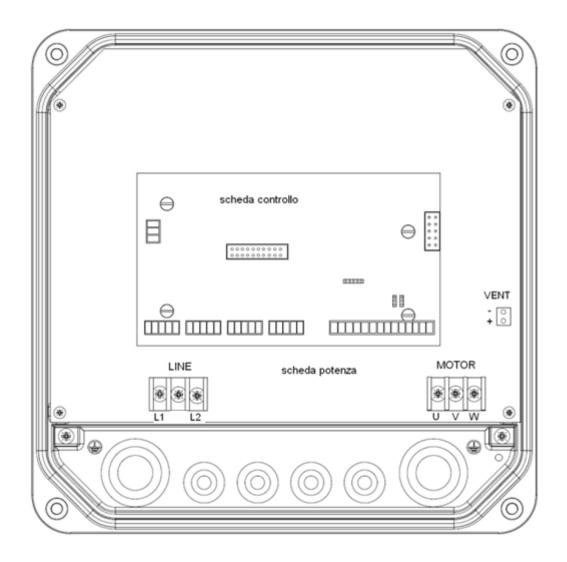
GND,U,V,W,

1 ph motor:
earth, U (running), V (common)
It is recommended to use cable lugs.

Recommended line and motor cables stripping



Power board VASCO 218, 225



Power supply:

LINE: L1, L2, GND

It is recommended to use cable lugs.

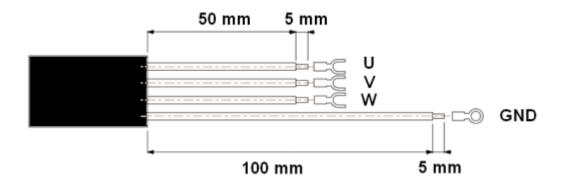
Motor output:

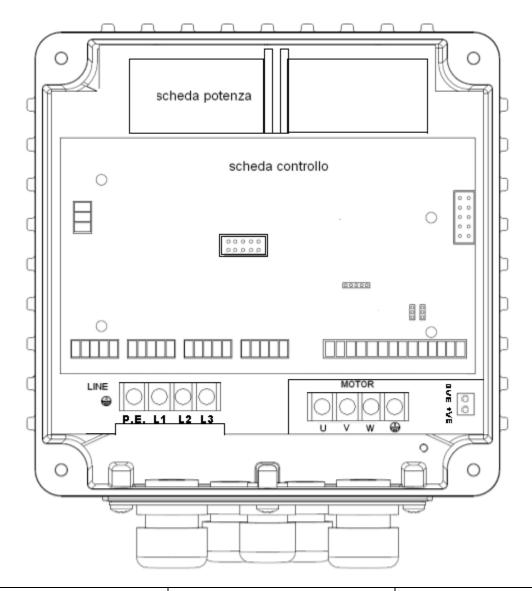
MOTOR: U, V, W, GND

It is recommended to use cable lugs.

12 V dc auxiliary fans (wall mounting kit)

VENT: +,
WARNING: respect the polarity.





Power supply:

LINE: GND , L1, L2, L3,

It is recommended to use cable lugs.

Motor output:

MOTOR: U, V, W, GND

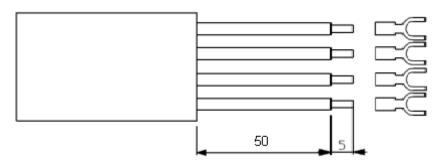
It is recommended to use cable lugs.

12 V dc auxiliary fan (wall

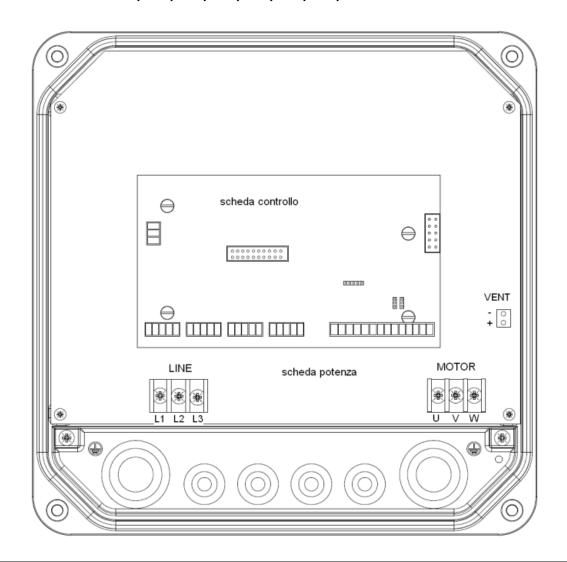
mounting kit):

OVE, + VE

WARNING: respect the polarity.



Power board VASCO 314,318,325,330,414,418,425,430



Power supply:

LINE: L1, L2, L3, GND

It is recommended to use cable

lugs.

Motor output:

MOTOR: U, V, W, GND

It is recommended to use cable

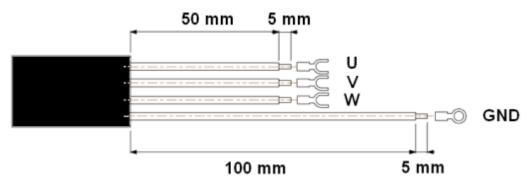
lugs.

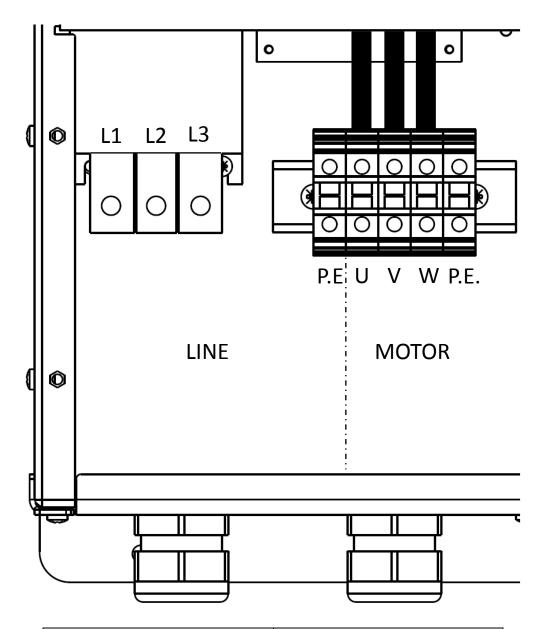
12 V dc auxiliary fans (wall

mounting kit)

VENT: +, -

WARNING: respect the polarity.





Power supply:

LINE: L1, L2, L3, P.E.

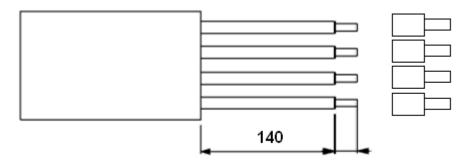
It is recommended to use cable lugs.

Motor output:

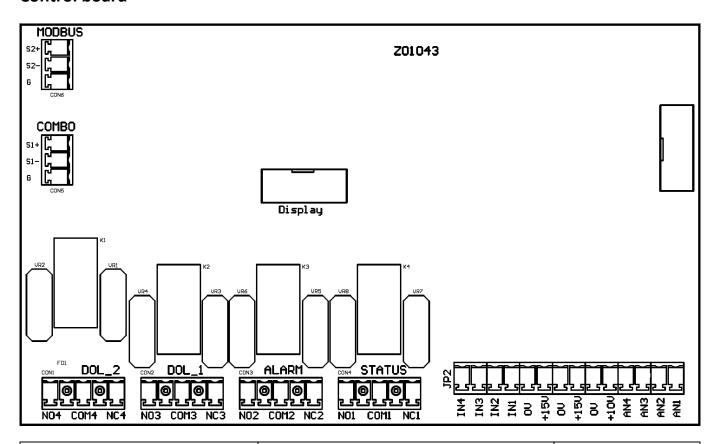
MOTOR: U, V, W, P.E.

It is recommended to use

cable lugs.



Control board



Analog inputs (10 or 15 Vdc):

- 1. AN1: 4-20 mA: sensor 1
- 2. AN2: 4-20 mA: sensor 2
- 3. AN3: 4-20 mA / 0 10 Vdc (settable by jumper C.C.): external set
- **4.** AN4: 4-20 mA / 0 10 Vdc (settable by C.C.): trimmer for frequency regulation / external set 2

Digital inputs:

- IN1 : motor start & stop
- IN2: value set 1 & 2 switching
- IN3: sensor 1 & 2 switching
- IN4: motor start & stop + alarms reset
- 0V

We recommend using only no voltage contacts.

Opening or closing the digital contacts (depending on software configuration set (see IN/OUT. parameters) you can start or stop the motor.

Digital outputs:

motor run signal:

NO1, COM1: closed contact with motor running. NC1,COM1: closed contact with motor stopped.

alarm signal

NO2,COM2: closed contact without alarm. NC2,COM2: closed contact with alarm or no power supply.

DOL1 pump relay:

NO3,COM3: closed contact with DOL1 running. NC3,COM3: opened contact with DOL1 running.

DOL2 pump relay:

NO4,COM4: closed contact with DOL2 running. NC4,COM4: opened contact with DOL2 running.

Relays are no voltage contacts. Max. voltage to the contacts is 250 V with max current of 5 A.

RS485 for COMBO:

- S1+
- S1-
- G

It is recommended to respect the polarity linking more VASCOs in series.

RS485 for MODBUS:

- S2+
- S2-
- G

It is recommended to respect the polarity.

4.1 Protections

The protections required upstream each VASCOs depends on the type of installation, and local regulations. We recommend to use overload protection with the characteristic curve of type C and type B circuit breaker, sensitive to both AC and DC current.

4.2 Electromagnetic compliance

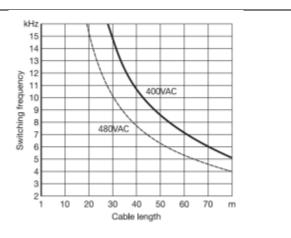
To ensure electromagnetic compatibility (EMC) of the system, it is necessary to apply the following measures:

- Always connect the device to ground
- Use shielded signal cables by placing the screen at one end.
- Use motor cable as short as possible (<1 m / <3 ft). For longer lengths, it is recommended to use shielded cables connecting the screen at both ends.
- Separate signal, motor, and power supply cables.

Note: To enable the restoration of the display screen when there are electromagnetic interference, VASCO periodically provides some fast "refresh" of the display.

4.3 Installation with long motor cables

With long motor cables it's recommended to decrease the commutation frequency from 10 kHz (default) to 2.5 kHz (Motor parameters). This reduces the probability of voltage spikes in the motor windings which may damage the insulation.



To prevent dangerous overheating of dv / dt and sinusoidal filters it is recommended to set the correct PWM value in relation to the cable length.

For motor cable lengths up to 50 meters it's recommended to place between VASCO and motor a dv / dt reactance, available on request.



For motor cable lengths greater than 50 meters it's recommended to place between VASCO and motor a sinusoidal filter, available on request.



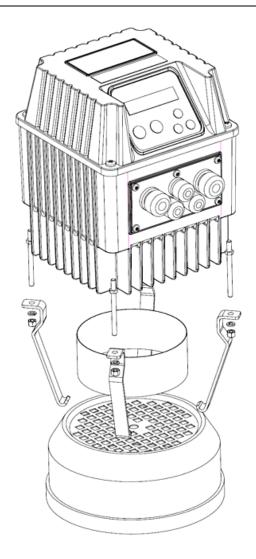
5. VASCO installation

VASCO can be installed directly on the fan cover of the motor or mounted on the wall.

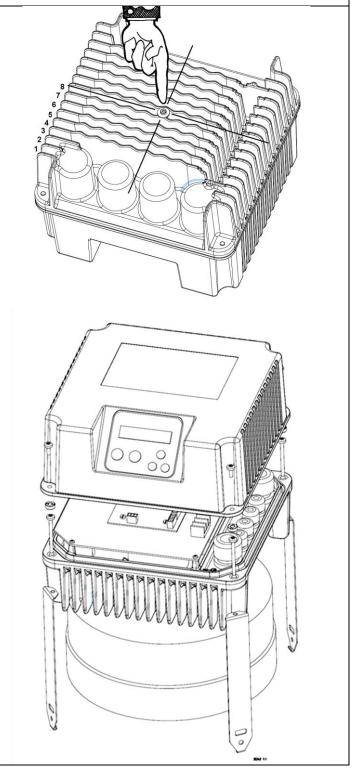
Motor mounting kit

In this application VASCO is cooled by the motor fan. Motor kit (available upon request) allows a solid coupling of the two units and it is composed of:

| VASCO SIZE 1 | VASCO SIZE 2 |
|----------------------------------|---|
| n.°4 rods | n.° 4 M5 screws. |
| n.°4 M5 nuts | • n.° 4 clamps |
| n.° 4 hooks | n.° 4 clips to add if necessary |
| • n.° 1 cooling ring | n.°1 centre pin |

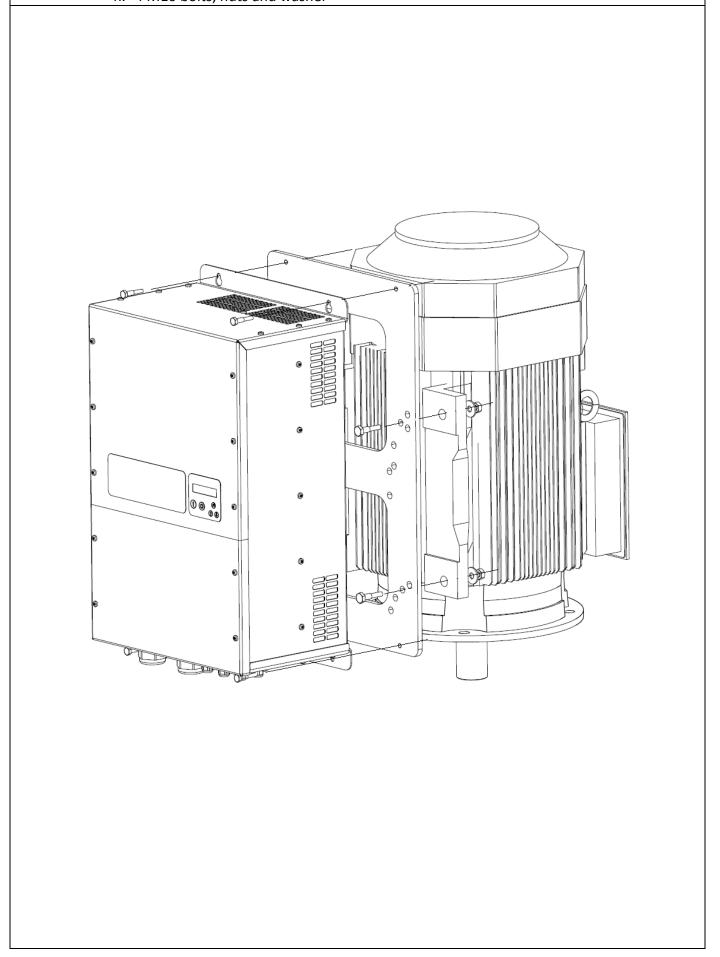


Use the cooling ring for best cooling of VASCO during operation. Warning: when using the cooling ring, the cooling air of the motor is slightly warmer than without the VASCO; if the resulting motor temperature exceeds the indicated maximum allowable value, remove the cooling ring, leaving the VASCO to be cooled by itself.



VASCO SIZE 3

- n.° 1 motor feet adaptor for MEC160,180,200,225
- n.° 4 M8 bolts,
- n.° 4 M10 bolts, nuts and washer

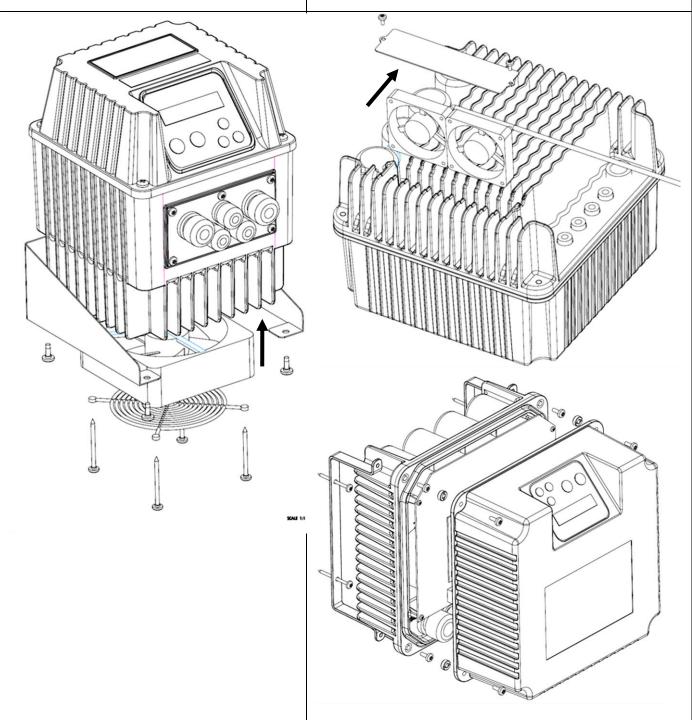


Wall mounting kit

In this application VASCO is cooled independently by its auxiliary cooling fan integrated in the radiator.

Wall-mounted kit is composed of:

VASCO SIZE 1 n.° 1 auxiliary fan 230V AC (VASCO 209,214) or 12 VDC (VASCO 306,309,406,409) n.° 4 screws to fix cooling fan n.° 1 fans cover. n.° 2 fans cover fixing screws n.° 2 fans cover fixing screws n.° 2 wall fixing brackets n.° 4 was cover fixing screws n.° 2 wall fixing brackets n.° 4 was cover fixing screws n.° 2 wall fixing brackets n.° 4 was cover fixing screws n.° 2 wall fixing brackets n.° 4 was cover fixing screws n.° 1 holes reference sheet



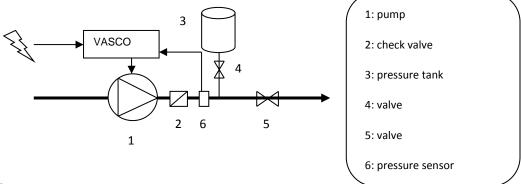


Make sure the manufacturer that the electric motor is suited for operation in the inverter Make sure to properly attach the grid of the auxiliary cooling fan.

Make sure to remove the auxiliary cooling fan if VASCO is coupled to a motor. Failure to do so creates a high risk of overheating the motor and VASCO unit.

5.1 VASCO Installation for constant pressure control

VASCO controls the pump speed to maintain constant pressure at a set point independent of the water demand in the system. A basic schematic is shown below:



5.1.1 Pressure tank

Installation of a pressure tank in the hydraulic system is recommended to compensate leakage of water in the system (or during minimum water demand) and to avoid continuous start/stop cycling of the pump (check the appendix for more information). Selecting the proper volume and pre-charge pressure of the tank is very important; smaller tank volumes will not compensate adequately for minimum water usage or leakage, while larger volumes make it more difficult for VASCO to control the pressure evenly.

Recommended tank volume is equal to the 10% of the maximum water flow of the system (expressed in volume unit/min)

Example: if the max water flow is 50 liters/min, the pressure tank should have a capacity of 5 liters

If the max water flow is 20 gpm, the pressure tank should have a capacity of 2 gallons

Pre-charge pressure of the pressure tank should be at least 80% than the set-pressure of the system.

Example: if the set-pressure of the system is 4 bar, the pre-charge pressure of the tank should be 3.2 bar

If the set-pressure of the system is 60 psi, the pre-charge pressure of the tank should be 48 psi

5.1.2 Pressure sensor

VASCO requires a pressure sensor with a linear output signal within the range 4 – 20 mA. The pressure transducer can be powered by any range of DC Voltage which includes the value 15 V dc.

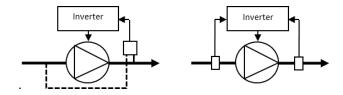
VASCO accepts the signal of a second pressure sensor in order to:

- realize constant differential pressure (AN1 AN2).
- substitute first pressure sensor when it fails
- switch pressure sensor by closing digital input IN2

| SENSOR 1 | AN1: 4-20 mA (-) signal +15V: 15 Vdc (+) power supply |
|----------|--|
| SENSOR 2 | AN2: 4-20 mA (-) signal +15V: 15 Vdc (+) power supply |

5.2 VASCO installation for differential constant pressure applications

VASCO can manage the pump speed in order to keep constant the pressure difference between the dischage and suction side of the pump in circulation systems. To do this, it is usually installed a differential pressure sensor. Alternatively, it is possible to use two identical pressure sensors: one in suction side and one in discharge side of the pump. The difference of values is performed by the VASCO itself.



N.B. If during the operation it is expected that the pressure in the suction side falls below the atmospheric pressure, it is necessary to use absolute pressure sensors and not relative ones.

5.2.1 Sensors wiring

The VASCO can be connected to linear pressure sensors with 4 - 20 mA output. The supply voltage range of the sensors must include the 15 VDC with which the VASCO feeds the analog inputs.

If you are using a differential pressure sensor it is necessary to connect the sensor to the analog input 1:

| DIFFERENTIAL SENSOR | AN1: 4-20 mA (-) signal |
|---------------------|---------------------------|
| | • +15V: 15 Vdc (+) supply |

In case two pressure sensors are used, the pressure sensor in the discharge side must be connected to the analog input 1 while the pressure sensor in the suction side must be connected to the analog input 2:

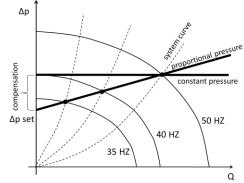
| SENSOR 1 (discharge) | AN1: 4-20 mA (-) signal +15V: 15 Vdc (+) supply |
|----------------------|--|
| SENSOR 2 (suction) | AN2: 4-20 mA (-) signal+15V: 15 Vdc (+) supply |

In the IN/OUT parameters menu it is therefore necessary to set the logic AN1, AN2 as "difference".

5.2.2 Programming

In circulation systems pump starting and stopping is usually controlled by an external contact that can be connected to the digital input 1 (IN1, 0V) and configured as N.O or N.C in the IN/OUT parameters menu. It is then recommended to set the following parameters:

| Control parameter | Recommended value |
|-------------------|---------------------------------|
| Freq. min control | Same as minimum motor frequency |
| Delta control | 0 bar |
| Delta start | 0 bar |
| Stop delay | 99 sec |
| IN/OUT parameter | Recommended value |
| Function AN1,AN2 | Difference 1-2 |



Constant differential pressure

The "set value" corresponds to the differential pressure to be kept constant.

Set the "set value" equal to the pressure difference measured between the discharge and the suction side of the pump at maximum load (all utilities opened) and at maximum frequency (50 Hz).

Proportional differential pressure

In case it is needed to use a control logic based on proportional differential pressure (in order to achieve a further energy saving), it is necessary to set the "set value" equal to the pressure difference between the discharge and suction side of the pump at minimum frequency (20 Hz) and "compensation" in order to reach the maximum set value at maximum frequency (50 Hz) and maximum load (all utilities opened).

6. VASCO Use and Programming

VASCO software is extremely simple to use, but allows a wide variety of parameters to be set for ideal system calibration. Setting Parameters are organized in 2 levels:

1: Installer level (MENU' CONTROL PARAMETERS, MENU' IN/OUT PARAMETERS, MENU' CONNECTIVITY PARAM.)

A password is required for this level; these parameters are adjustable by trained professionals

Default password: **001**

From the menu a different password can be set up.

2. Advanced level (MENU' MOTOR PARAMETERS)

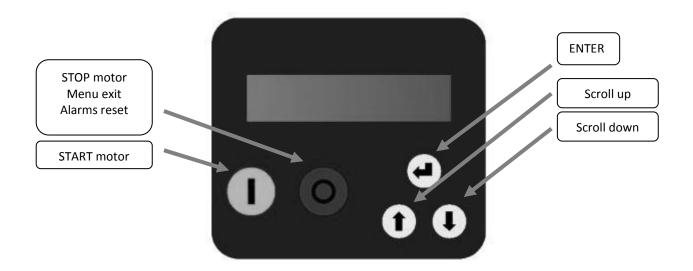
A second and different password is required; improper setting of these advanced parameters could compromise the integrity and the life of VASCO and pump;

Default password **002**

It is possible to set up a different password.

Installer and Advanced levels can be entered only with the correct password; otherwise, it is impossible to set up and/or modify any parameters (they can be only displayed).

6.1 VASCO display



Screen is a back-lit LCD displaying 2 rows of 16 digits each. Alarms are indicated by an audible signal.

6.2 Initial configuration

When VASCO is switched on for the first time, the initial setting menu is displayed for the initial setting of parameters to configure pump characteristics, pressure sensor range, and system characteristics.

If the initial setting procedure is not completed properly, it is impossible to run the pump. Initial setting procedure can be repeated if necessary.

The initial setting procedure can be repeated (by using the 2rd level password) to reconfigure VASCO or if VASCO is installed in a different system.

A brief description of parameters and their allowable ranges are listed below:

| | Parameter | Default | Description |
|------|------------------------|------------|---|
| | Language | | End user communication language |
| | VVVVV | XXXX | |
| | XXXXXX | | |
| Unit | | | Unit |
| | xxxxx | bar | |
| | XXXXX | | |
| | Motor type | threephase | Type of motor connected (VASCO 209,214) |
| | singlephase/threephase | | |
| | | | |
| | Rated motor Amp. | | Rated current of the motor per it's nameplate indication increased by 10%. The voltage drop caused by the inverter leads to higher |
| | I = XX.X [A] | XX | input current than nominal. Make sure motor is capable of |
| | | | accepting increased current. |
| | Rated motor freq | | Rated frequency of the motor per its nameplate. |
| | f = XXX [Hz] | 50 | |
| | | Control | mode: Constant value [bar] |
| | F. scale sensor | Control | noue. Constant value [bar] |
| | 1. Scale Selisoi | 16 | Sensor full scale. |
| | p = XX.X [bar] | | |
| | Sensor test | | If the transducer is not connected or connected improperly, the |
| | | | signal SENSOR OFF is activated when pressing ENTER. |
| | Press ENT | | |
| | Max alarm value | | Maximum pressure allowed in the system. If the pressure goes over |
| | | 10 | this value, an alarm occurs and the pump is stopped. Pump is automatically restarted if the pressure goes below the maximum |
| | p = XX.X [bar] | | value for a period of at least 5 seconds. |
| | Set value | | The pressure value to be kept constant. |
| | . VV V [hau] | 3 | |
| | p = XX.X [bar] | | |
| | Motor test | | Press START/STOP to run a test at rated frequency Warning: make sure to run the system without damaging pump |
| | START/STOP | | and system |
| | 3174(1/3101 | | |
| | Rotation sense | | If, during the test, the motor runs in reverse, it is possible to change the wiring sequence via software without physically changing wires |
| | > / < | > | at the terminals. |
| | , | | |
| | СОМВО | | Activation or deactivation of COMBO operation. |
| | ON/OFF | OFF | |
| | | | If ON is selected, after a lack of voltage, VASCO returns to its normal |
| | Autorestart | 055 | status; if VASCO was powering the pump before the voltage drop, it |
| | ON/OFF | OFF | resumes powering the pump automatically. |
| | INITIAL SETUD | | Warning, review the advice in chapter 1 Once the Setting procedure is completed you will get this indication |
| | INITIAL SETUP | | on the display; setting parameters are recorded by VASCO; these |
| | COMPLETED | | parameters can be set up individually in the parameters menu. |
| | | I . | |

6.3 Initial view

When first powering the VASCO, the display shows: release of display software (LCD = X.XX) and the release of inverter software (INV = X.XX) as shown below:

LCD = X.XX

INV = X.XX

The following End User messages are displayed by pushing the scroll buttons:

| | p is the pressure value read by the pressure transducer. |
|-------------------------|---|
| Inv: ON/OFF Mot: ON/OFF | By pressing ENTER the pressure set value is displayed <xxx.x></xxx.x> |
| p = XX.X [bar] | |
| Inv: ON/OFF Mot: ON/OFF | f value is the supply frequency to the motor; On fix frequency control mode, by pressing ENTER you can change the f value manually (word "set" is displayed), |
| f = XXX [Hz] | press ENTER again to exit parameter setting (word "set" disappeared). |
| Inv: ON/OFF Mot: ON/OFF | V_in is the line voltage. This value is displayed only if motor is OFF; if motor is ON, A value equal to the absorbed motor current. |
| V_in = X.XX [V] I= XX.X | |
| Inv: ON/OFF Mot: ON/OFF | cosphi index means the angle phi between the voltage and current absorbed by the motor |
| cosphi = XXX | |
| Inv: ON/OFF Mot: ON/OFF | P is the power in Watts supplied to the pump. |
| P = XXXXX [W] | |
| Inv: ON/OFF Mot: ON/OFF | NORMAL status means no alarms. If an alarm occurs, a message blinks on the display and an audible signal is |
| STATUS: NORMAL | activated. Pressing ENTER accesses: VASCO lifetime, PUMP lifetime, consumption statistic, |
| Inverter Life | alarm list. To return to previous views, press ENTER. |
| xxxxx h : xx m | |
| Motor Life | |
| xxxxx h : xx m | |
| %f 25 50 75 100 | |
| %h XX XX XX | |
| xxxxxxxxxxxx | |
| XXXXXXXX h : XX m | |
| Menù | |
| ENT to access | |
| | |

First row gives the VASCO status:

- Inv: ON XXX.X Hz VASCO is powered and is powering the motor showing its frequency.
- **Inv: ON Mot: OFF** VASCO is powered but motor is not running (i.e. motor/pump was stopped due to minimum frequency being reached)
- Inv: OFF Mot: OFF VASCO is not powered

If COMBO function is activated, the VASCO address is placed close to indication "Inv".

6.4 Menu view

Pressing ENTER when you are in [MENU' / ENT to access] in initial display, will display the following MENUs:

| MENU' | Installer password required to enter level 1 (default 001) |
|------------------|--|
| Control. param. | |
| MENU' | Advanced password required to enter level 2 (default 002) |
| Motor param. | |
| MENU' | Installer password required to enter level 1 (default 001) |
| IN/OUT. param. | |
| MENU' | Installer password required to enter level 1 (default 001) |
| Connect. param. | |
| MENU' | Advanced password required to enter level 2 (default 002) |
| Change init.set. | |

To exit the Menu level and return to initial display, press STOP button.

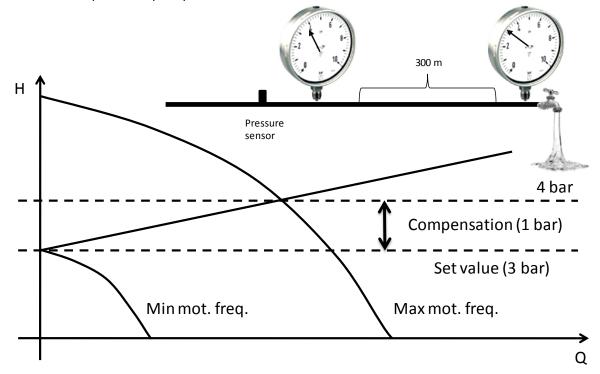
6.5 Control parameters

| Parameter | Default | Description | Constant value | Fix speed | Const.value 2 set | Fix speed 2 val. | External speed |
|---|----------------|---|--------------------------------|--------------------|-------------------------------|------------------|-----------------------|
| Control mode Constant value Fix speed Const.value 2set Fix speed 2 val. External speed | Constant value | Constant value: VASCO changes the value constant regardless water does not not not not not not not not not not | emand. at set f are sele | frequer ected b | ncy, so y openi ening o | the puning or cl | np losing g the |

| Parameter | Default | Description | Constant value | Fix speed | Const.value 2 set | Fix speed 2 val. | External speed |
|------------------------------|---------|--|----------------|-----------|-------------------|------------------|----------------|
| Max alarm value XXX.X [bar] | 10 | Maximum value allowed in the system. If the readen value goes over this value, an alarm occurs and the pump is stopped. Pump is automatically restarted if the readen value goes below the maximum value for a period of at least 5 seconds. | ✓ | ✓ | ✓ | ✓ | ✓ |
| Min alarm value XXX.X [bar] | 0 | Minimum value allowed in the system. If the readen value goes lower than this value, an alarm occurs and the pump is stopped. Pump is automatically restarted if the readen value goes higher than the minimum value for a period of at least 5 seconds. | ✓ | ✓ | ✓ | ✓ | ✓ |
| Ext.set enabling ON/OFF | OFF | Enabling of set value changing by analog input AN3. | ✓ | | ✓ | | |
| Set value XXX.X [bar] | 3 | Set value to be kept constant. | ✓ | | | | |
| Compensation XXX.X [bar] | 0 | Value compensation at the maximum frequency for each pump. Acting on the green button you can reverse the sign. | √ | | | | |
| Set value 2 XXX.X [bar] | 3 | Set value to be kept constant. | | | √ | | |
| Compensation 2 XXX.X [bar] | 0 | Value compensation at the maximum frequency for each pump. Acting on the green button you can reverse the sign. | | | ✓ | | |
| Set value update XX [s] | 5 | Time to update set value for compensation. | ✓ | | ✓ | | |

| Parameter Default | Description | Constant value | Fix speed | Const.value 2 set | Fix speed 2 val. | External speed |
|-------------------|-------------|----------------|-----------|-------------------|------------------|----------------|
|-------------------|-------------|----------------|-----------|-------------------|------------------|----------------|

To ensure proper operation of pressure control is recommended to place the sensor near the pump. To compensate the pressure loss in the pipes (proportional to flow) it is possible to vary the pressure set in a linear relation with respect to frequency.



It can perform the following test to verify the correct value of compensation:

- 1. install a pressure gauge away from the pressure sensor
- 2. open completely the valve
- 3. check the pressure gauge
- --> Set the value of *compensation*. equal to the difference of the values from the two gauges.

When using a group of pumps, the pressure compensation to be applied to each pump is equal to the total pressure compensation (when all the pumps are running at full speed) divided by the number of pumps in the group.

| Operating freq. XXX [Hz] | 50 | Frequency value to feed the pump. | | √ | | | |
|-----------------------------|----|--|----------|----------|----------|----------|----------|
| Operating freq. 2 XXX [Hz] | 50 | Frequency value to feed the pump. | | | | ✓ | |
| Freq.min.control XXX [Hz] | 50 | Minimum frequency below which the pump tries to stop. | √ | | ✓ | | ✓ |
| Stop delay XX [s] | 5 | Delay for which the pump tries to stop below freq.min.control. | √ | | √ | | ✓ |
| Control ramp XXX.X [s] | 20 | Ramp time from freq.min.control to min.motor freq. If, during this time, the read value goes below the (set value - delta control), VASCO powers the motor | ✓ | | ✓ | | ✓ |

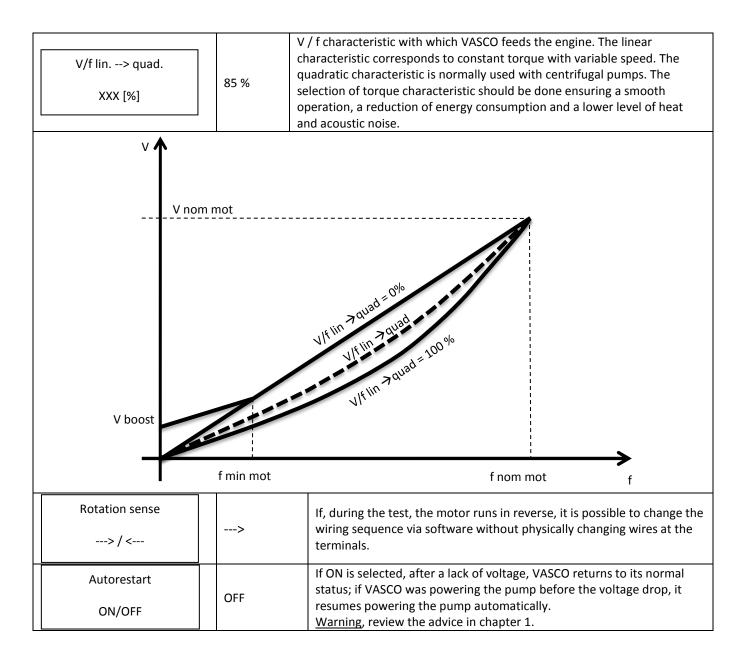
| Parameter | Default | Description | Constant value | Fix speed | Const.value 2 set | Fix speed 2 val. | External speed |
|-----------------------------------|-------------|--|----------------|-----------|-------------------|------------------|----------------|
| | | again; otherwise, VASCO will stop the pump. | | | | | |
| Delta control XXX.X [bar] | 0.1 | Value drop below the set value required to restart the pump during control ramp. | ✓ | | ✓ | | |
| Hz | Delta contr | ol 🏂 | | | press., | | |
| Freq.min.control Min mot. freq | | Stop delay Control ra | amp | | | | |
| Delta start XXX.X [bar] | 0.5 | Value drop below the set value required to start the pump from stop condition. | ✓ | | sec | | |
| Delta stop XXX.X [bar] | 0.5 | Value increase respect to set value which must be passed so that there is a forced shutdown of the pump. | ✓ | | ✓ | | |
| Кр | | Kp and Ki parameters allow the dynamic control of system by VASCO; set values (Ki=50, Kp=005) are usually enough to get a valid dynamic control. | ✓ | | ✓ | | |
| Pump DOL 1 ON/OFF | OFF | Function to activate (ON) the first auxiliary pump DOL 1 (Direct On Line pump). | ✓ | | ✓ | | |
| Pump DOL 2 ON/OFF | OFF | Function to activate (ON) the second auxiliary pump DOL 2 (Direct On Line pump). | | ✓ | | | |
| COMBO ON/OFF | OFF | Enabling or disabling COMBO operation as described in COMBO chapter. | ✓ | | ✓ | | |

| Parameter | Default | Description | Constant value | Fix speed | Const.value 2 set | Fix speed 2 val. | External speed |
|--------------------------------|---------|--|----------------|-----------|-------------------|------------------|----------------|
| Address XX | 00 | VASCO address: • 00 master • 01 to 07 slaves | ✓ | | ✓ | | |
| Alternance ON/OFF | OFF | Function to allow alternating between the VASCOs connected in COMBO (or pumps connected in DOL) in order to allow equal use of each pump in the group; master will reorganize the starting priority of the pumps by checking the life of each of them. | ✓ | | ✓ | | |
| Alternance period XX [h] | 0 | Maximum difference in terms of hours between VASCOs in the group. 0 stays for 5 minutes. | ✓ | | ✓ | | |
| Start delay AUX t = XX [s] | 0 | Delay time with which the slaves start after the variable speed pump has reached the maximum frequency and the pressure value has fallen below set value – delta control | ✓ | | ✓ | | |
| PI control Direct/Reverse | Direct | Direct: increasing motor speed also misured value increases Reverse: increasing motor speed, misured value decreases. | ✓ | | ✓ | | |
| Periodic autorun t = XX [h] | 0 | Pump periodic autorun after XX hours of inactivity. Value 0 makes function disabled. Warning, review the advice in chapter 1. | ✓ | ✓ | ✓ | ✓ | ✓ |
| Dry run cosphi X.XX | 0.65 | Cosphi value below which the unit stops the motor and give "no water" alarm. | ✓ | ✓ | ✓ | ✓ | ✓ |
| Restarts delay XX [min] | 10 | Restart delay after a dry running alarm. At each tentative (max 5) restart delay will be doubled. | √ | ✓ | ✓ | ✓ | ✓ |

6.6 Motor parameters

| Parameters | Default | Description |
|-------------------|---------|--|
| Rated motor Volt. | | |
| XXX [V] | XXX | Motor rated voltage (as shown on motor nameplate). |

| Voltage boost XX.X [%] | 0% | Voltage increase during the motor start up. Warning: An excessive value can seriously damage the motor. Contact the motor manufacturer for further information. | | |
|------------------------------|----------------------------|--|--|--|
| Rated motor Amp. XX.X [A] | xx | Rated motor current as per its nameplate indication increased by 5%. | | |
| Rated motor freq XXX [Hz] | 50 | Rated motor frequency as per its nameplate. | | |
| Max motor freq. XXX [Hz] | 50 | Maximum motor frequency. Note: by reducing the maximum motor frequency, maximum current will be reduced as well. | | |
| Min motor freq. XXX [Hz] | 20 | Minimum motor frequency. | | |
| Ramp up time XXX.X [sec] | 4 | Ramp-up time to reach the speed required to achieve the set pressure (or frequency value). Longer times delay the system reaching the preset value but better protect system components. Excessively long ramp-up times can create difficulties in VASCO setup, and can also cause false overload alarms. | | |
| Ramp down time XXX.X [sec] | 4 | Ramp-down time to reach zero speed. Longer times keep the system pressurized, while protecting the system components. Excessively long ramp-down times can create difficulties in VASCO setup. Excessively short ramp-down times can cause false overload alarms. | | |
| Ramp f min mot. XXX.X [sec] | 1.5 | Time to reach the minimum motor frequency and vice versa. | | |
| Freq. ^ | | Max motor freq. Ramp down time Stop delay Freq.min.control | | |
| 0 | Min. mo Ramp f min mot. | ctor. freq. Ramp f min mot. | | |
| PWM XX.X [kHz] | 8 | Carrier frequency (switching frequency). It is possible to choose PWM in the range of 2.5,4,6,8,10 kHz. Higher values give a more sinusoidal wave with fewer losses for the motor but higher losses for the inverter (increased inverter heating). If long cables are used (>20 m / >76 ft) (submersible pump) it is recommended to install an inductive filter between VASCO and the motor (available upon request) and to set the value of PWM to 2.5 kHz. This reduces the risk of voltage spikes, which can damage motor and cable insulation. | | |



6.7 IN/OUT parameters

| Parameter | Default | Description | |
|------------------|---------|--|--|
| Unit | bar | Unit [bar,%,ft,in,cm,m,K,F,C,gpm,I/min,m3/h,atm,psi] | |
| xxxxx | bui | | |
| F. scale sensor | 16 | Sensor full scale. | |
| XXX.X | | | |
| Min.value sensor | 0 | Sensor minimum value. | |
| XXX.X | | | |
| Offset input 1 | 20% | Zero correction for analog input 1 (4-20 mA) (20 mA x 20% = 4 mA). | |
| [%] | 2070 | | |

| Parameter | Default | Description |
|--------------------------------|-------------|---|
| Offset input 2 [%] | 20% | Zero correction for analog input 2 (4-20 mA) (20 mA x 20% = 4 mA). |
| Offset input 3 [%] | 0% | Zero correction for analog input 3 (0-10V) $(10V \times 00\% = 0 \text{ V}).$ |
| Offset input 4 [%] | 0% | Zero correction for analog input 4 (0-10V) $(10V \times 00\% = 0 \text{ V}).$ |
| AN1,AN2 function XXXXXX | Independent | Function logic for analog input AN1,AN2 (independent, lower value, higher value, difference 1-2). |
| Digital input 1 N.O. / N.C. | N.O. | By selecting N.O. (normally open) VASCO runs the motor if the digital input 1 is open; motor will be stopped if the digital input 1 is closed. By selecting N.C. (normally closed) VASCO runs the motor if the digital input 1 is closed; motor will be stopped if the digital input 1 is opened. |
| Digital input 2 N.O. / N.C. | N.O. | By selecting N.O. (normally open) VASCO runs the motor if the digital input 2 is open; motor will be stopped if the digital input 2 is closed. By selecting N.C. (normally closed) VASCO runs the motor if the digital input 2 is closed; motor will be stopped if the digital input 2 is opened. |
| Digital input 3 N.O. / N.C. | N.O. | By selecting N.O. (normally open) VASCO runs the motor if the digital input 3 is open; motor will be stopped if the digital input 3 is closed. By selecting N.C. (normally closed) VASCO runs the motor if the digital input 3 is closed; motor will be stopped if the digital input 3 is opened. |
| Digital input 4 N.O. / N.C. | N.O. | By selecting N.O. (normally open) VASCO runs the motor if the digital input 4 is open; motor will be stopped if the digital input 4 is closed. By selecting N.C. (normally closed) VASCO runs the motor if the digital input 4 is closed; motor will be stopped if the digital input 4 is opened. |
| Dig.In.2/3 delay [s] | 3 | Digital input IN2 & IN3 delay. Digital input IN1 has 1 second fix delay. |

6.8 Connectivity parameters

| Parameters | Default | Description |
|--------------------|---------|--|
| MODBUS address | | |
| xxx | 1 | MODBUS address from 1 to 247 |
| MODBUS baudrate | | |
| XXXXX [bps] | 9600 | MODBUS baudrate from 1200 bps to 57600 bps |
| MODBUS data format | RTU N81 | |
| xxxxx | 51101 | MODBUS data format: RTU N81, RTU N82, RTU E81, ETU O81 |

7. Protections and alarms

Anytime a protection occurs a blinking message is displayed together with an audible alarm; on STATUS in the initial view, the protection is displayed; by pressing the STOP button. Only from this position (STATUS) in the initial view is it possible to try to reset the alarm; if VASCO does not reset the alarm it is displayed again together an audible sound.

| ALARM MESSAGE | ALARM DESCRIPTION | POSSIBILE SOLUTIONS |
|------------------------------|--|---|
| OVERCURRENT MOT. | Motor overload: input current of the motor is higher than the rated motor current setting parameter. Motor voltage drop caused by the inverter causes the motor input current to be higher than rated. Contact motor manufacturer to check if motor is capable of accepting this current. | Make sure that the motor current setting parameter is higher than rated. Check other possible causes of over current |
| UNDER VOLTAGE | Supply voltage too low | Check possible causes of undervoltage |
| OVER VOLTAGE | Supply voltage too high | Check possible causes of overvoltage |
| OVER TEMP. INV. | Inverter over temperature | Make sure than ambient temperature is less than 40 °C (104 °F). Check if auxiliary cooling fan is working properly and if mounting space is adequate for proper cooling. Reduce the PWM value (Advance Parameter Menu) |
| NO LOAD | No load | Check if load is properly connected to the VASCO terminals |
| NO WATER (DRY RUN COSPHI) | Motor cosphi is lower than the set value of dry running cosphi | Check if the pump is primed Check the set value of dry running cosphi. Dry running cosphi is approximately 60% of the rated cosphi (at rated frequency) listed on the motor plate. If pump's cosphi is lower than the set dry-running cosphi for at least 2 seconds, VASCO stops the pump. VASCO tries to run the pump every 10, 20, 40, 80, 160 minutes and then the pump is stopped. WARNING: if dry running protection occurs, VASCO will try to start the pump automatically. Be sure to cut power supply to VASCO before performing any maintenance. |
| SENSOR FAULT | Sensor error | Check the transducer Check the wiring of transducer |
| MAX. VALUE ALARM | Measured value has reached the maximum value accepted by the system. | Check possible causes of reaching max value Check the max alarm value setting |

| MIN. VALUE ALARM | Measured value has reached the lowest value accepted by the system. | Check possible causes reaching min value (i.e. broken pipe, open pressure relief valve, etc.) Check the min alarm value setting. | | | |
|---------------------|--|--|--|--|--|
| IGBT TRIP ALARM | The current drawn by the load exceeds the capacity of VASCO. VASCO is still able to continue to power the load for 10 minutes with an output current of 101% of nominal and for 1 minute with an output current of 110% of nominal | Increase the ramp-up time Make sure that the load current is at least 10% below the VASCO nominal current Check the voltage drop along the supply cable to the motor | | | |
| NO COMMUNICATION | Communication between Master and slave(s) has been interrupted | Check the wiring connections Make sure the Master is not in the Menu level; if so, exit from the level. In the STATUS of the slave (where the alarm is displayed) try to reset the alarm by pushing STOP button. | | | |
| ADDRESS ERROR | Same address as other VASCOs in the group | The address of each VASCO needs to be different | | | |
| KEYBOARD FAULT | A Button on the keyboard has been pressed for more than 150 seconds | Make sure buttons are not depressedCall service assistance | | | |
| ACTIVE DIG.IN.X | Digital input X opened /closed | Check the input digital configuration (IN/OUT Parameters menu) | | | |
| ALARM SLAVE XX | slave XX error detected by master | check the status of the slave | | | |
| | If pumps cosphi is lower than the dry-running cosphi for at least 2 seconds, VASCO will stop the pump. VASCO will try to run the pump every 10, 20, 40, 80, 160 minutes and then the pump is stopped. ATTENTION: if dry-running protection occurs, VASCO will try to start the pump automatically. Be sure to cut power supply before attempting maintenance VASCO will stop the pump if the input motor current is higher than the set motor current for an extended time. By pressing the START button it is possible to run the pump again. VASCO will stop the pump if the input voltage is higher than the set voltage for an extended time. By pressing the START button it is possible to run the pump again. VASCO will stop the pump if the input voltage is lower than the set voltage for an extended time. By pressing the START button it is possible to run the pump again. | | | | |

8. Auxiliary pumps during constant pressure control

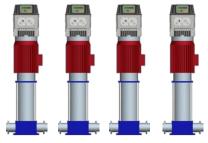
When the water needs vary considerably, it is advisable to share the water request between several pumps ensuring better efficiency and reliability.

A first method consists of a single pump driven directly by VASCO and another 1 or 2 pumps directly connected to the mains DOL (Direct On Line); DOL pumps are controlled by VASCO and connected to the mains through 1 or 2 contactors.



In this method, DOL pumps are not started and stopped smoothly with the corresponding increase in energy consumption and mechanical wear (startup current). Also note that DOL pumps are not protected by VASCO.

A second method of sharing water demand (named COMBO mode) consists of using additional pumps in parallel (up to 8), with each one driven by a VASCO.



In this method, energy consumption and reliability of the pumping system is maximized: VASCO monitors and protects each pump. It is possible to assemble a booster system composed of pumps connected in COMBO mode and another 1 or 2 DOL pumps to cover additional water demand (menaged only by master).



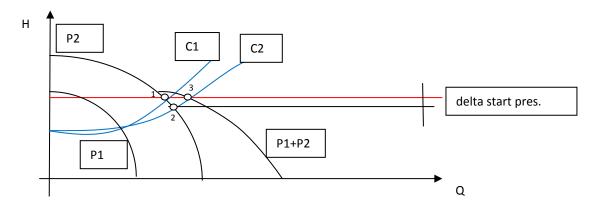
8.1 DOL pumps

Each DOL pump is switched on by a contactor controlled by the digital output DOL1 and DOL2 present in the VASCO.



VASCO relays driving the DOL pumps are relays with no voltage contacts. Max voltage to the contacts is 250 V, max current 5 A.

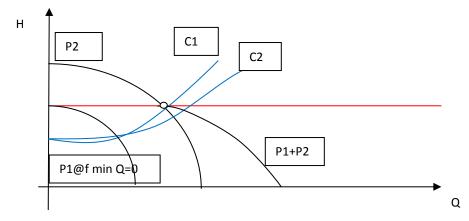
Two pumps are connected in parallel, with one pump (pump 1, P1) run by the inverter, while the second pump (pump 2, P2) is directly connected to the main power ("Direct On Line" connection). Start/Run of the second pump is controlled by the relay DOL1 (allowing a third pump to be controlled by the relay DOL2).



If pump 1 (P1) is already running to maintain the desired set pressure (red line), an additional water request changes the system curve from C1 to C2; since pump 1 (P1) is running at maximum speed, it is not possible to maintain the set pressure by increasing the speed, so the system pressure will drop till reaching the new working point 2.

If pressure at the point 2 is (set value – delta control), VASCO will run the DOL by relay DOL1. The DOL pump will run at its nominal speed while the pump 1 will drop it speed equal to the P1 pattern to maintain set pressure.

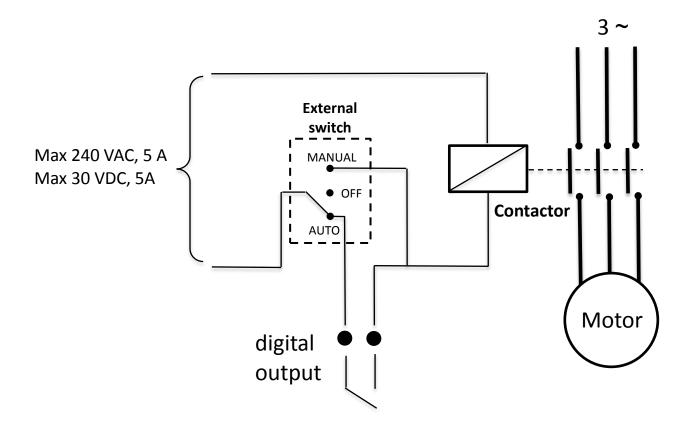
If water demands decreases, returning to the system curve C1, pump 1 will reduce the pump speed to maintain constant pressure in the system. When pump 1 reaches a frequency equivalent to the minimum frequency, while still maintaining set pressure, the DOL pump will be switched off and pump 1 will increase the speed to maintain the p set in the system.





If two pumps are connected in parallel, the first driven by VASCO and the second with a DOL connection, it is necessary makes sure that the value "delta control" will be sufficiently high to ensure the first pump, once the DOL pump is switched on, will reach a frequency higher than its minimum frequency value.

By proper setting of the minimum frequency, excessive pump ON/OFF cycling is avoided, thus preventing damage to the DOL pump.



8.2 COMBO function

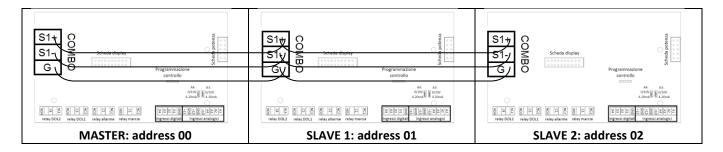
In the "Control parameters" menu it is possible to enable the COMBO function that allows serial communication between up to 8 VASCOs, each one connected to a pump. The operating principle (switch on/off) of pumps is similar to as stated in chapter 8.1.

To achieve the COMBO function in a system consisting of several interconnected VASCOs, use a pressure sensor connected to each VASCO. The value of the *set pressure* is communicated to the slaves via the serial port.

As a further help, you can connect another two DOL pumps to the VASCO Master to cover additional water demand; they will be operated only when all the COMBO pumps are already in operation.

RS485 serial connection

VASCO's communication is made through a private protocol using the RS485 port. Each VASCO must be connected to each other by using a tripolar cable (0,5 mm²) wired on S+,S-,G pins on control board.



Master setup

- 1. Supply power to the VASCO master.
- 2. If not yet completed, perform the initial configuration as described on chapter 6.2
- 3. Initial view is shown:

Inv: ON/OFF Mot: ON/OFF

p_mis=XX.X [bar]

4. Scroll until:

Menù

ENT to access

5. Press ENT

MENU'

Control. param.

- 6. Press ENT
- 7. Insert password (default 001).
- 8. Scroll until:

Combo

ON/OFF

- 9. Set ON
- 10. Set:

| А | ddress | 00 | VASCO's address in parallel operation. • 00: VASCO master | | |
|------------|-----------|-----|--|--|--|
| | XX | | | | |
| Alt | ernance | OFF | Function to allow alternating between the VASCOs connected in parallel in order to allow equal use of each pump in the group; in this way Master will reorganize | | |
| 0 | ON/OFF | | the starting priority of the pumps by checking the life of each of them. | | |
| Start | delay AUX | | Delay time with which the slaves start after the variable speed pump has reached the maximum frequency and the pressure value has fallen below set value — delta | | |
| t = XX [s] | | 0 | control | | |

- 11. Press STOP (red button)
- 12. Press STOP again

Slave setup

Follow Master setup until point 11.

In case of failure of master in a Combo system, will be replaced by slave. As a consequence, all parameters must be setup independently on each inverter, master mode.

1. Set:

| Address | VASCO's address in parallel operation. • 01> 07: VASCO slaves |
|---------|--|
| xx | of von video states |
| | |

- 2. Press STOP (red button).
- 3. In the *Motor parameters* verify that *Autorestart* is set *ON*.
- 4. Press STOP (red button).
- 5. Press STOP again.

Whenever the user accesses the Menu screen of the VASCO master, the communication between VASCOs is automatically interrupted.

In case of alarm or failure of a pump in a Combo system, this pump's operation will be replaced (temporary or permanently) by another pump.

In case of failure of master in a Combo system, it will be replaced by the next slave after about 1 minute. In order to enable master replacement Autorestart must be set ON in each slaves.

9. Trouble-shooting chart

| LCD does not switch on after powering the VASCO | Check the connecting flat cable between the LCD board (attached to the cover) and the control board Check the fuses Check that the power cables are properly connected. |
|---|--|
| Power line of VASCO is interrupted by the differential protection contactor | Check the leakage current to ground of EMC filter Following a rapid off/on the power supply, the differential contactor can interrupt the power. After turning off the VASCO it is recommended to wait at least 1 minute before restarting. |
| When performing sensor test operation, SENSOR OFF alarm occurs | Check that the sensor cable is properly connected to the sensor device and to the VASCO. Make sure that the sensor and its cable are not damaged. Check that the operating range of sensor is of 4 -20 mA type and the value of 15 V is within the voltage feed range of the sensor. |
| Frequency and pressure oscillation on constant pressure control mode | Check if the water tank and its air pressure are correctly set. It may be necessary to increase the tank volume or reduce the pre-charge pressure. Check the ki & kp parameters (Control parameters menu). At first, it is suggestable to increase the Ki value. If it not enough reduce of one unit the Kp value. |
| DOL pump stops and starts continuously | Increase delta control. Check to see if the water tank and it's air pressure are correctly set. It may be necessary to increase the tank volume or reduce the precharge pressure. |
| Measured pressure drops too much before VASCO starts the pump. | Decrease the delta start value (Control Parameters menu). Check to see if the water tank and it's air pressure are correctly set. It may be necessary to increase the tank volume or reduce the precharge pressure. Modify the value of ki & kp parameters (Control Parameters menu). At first, it is suggestable to reduce the Ki value. If it is not enough increase of one unit the Kp value. |

10. Technical Assistance

For more technical information contact the authorized reseller providing the following information. The solution to the problem will be found faster and easier if full information is provided.

| Model/Serial Code LCD version (shown who | | | en VASCO | | | own when VASCO is power | |
|--|---|------------------|-----------------------------|---------------------------|-------------------|-------------------------|--|
| supplied LCD = | | | | | supplied) INV = | | |
| | İ | | | | | | |
| Line Voltage: [V] | | Line Frequenc | cy: | 50 Hz | 60 Hz | | |
| description of problem: | | | | | | | |
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |
| installation type: | | w | all moun | ted | | on motor fan cover | |
| motor type: | | | single ph | ase | t | hree phase | |
| | | SI | ubmersib | le | su | rface | |
| if submersible: cable lenght [m]: | | | | if sul | section [mm²]: | | |
| P2 motor [kW]: | rated | motor Volt [V]: | | rated motor Amp [A]: | | rated motor Hz: | |
| | | | | | | | |
| if single phase: capacitor | | if singlephas | e: startin | ng Amp pump performai | | l ormances | |
| [UF] | | I st = | | | Q =[| /min] | |
| | | | | | H =[ı | n] | |
| | | | | | | | |
| tank volume: [liter | s] | | | precharge pressure: [bar] | | | |
| number of DOL pumps: _ | | | | number of COMBO pumps: | | | |
| medium ambient temper | ature: | | | pressure sensor | | | |
| [°C] | | | 4 mA =[bar] 20 mA =[bar] | | | | |
| | | | 20 | IIIA –[Dai] | | | |
| digital inputs used: | | | | digital ouputs us | sed: | | |
| | | | | | | | |
| electric and hydraulic sch | eme of th | e system (more | e detailed | l as possible) | | | |
| | | | | | | | |
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| | | | | | | | |
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| | | | | | | | |
| | | | | | | | |
| | | | | | | | |
| | set parameters: please fill the instal. param. and adv. param columns in the software scheme. | | | | | | |
| set parameters: please fil | I the insta | il. param. and a | adv. para | m columns in th | ne software scher | ne. | |

DECLARATION OF CONFORMITY

| In accord | ling | with: |
|-----------|------|-------|
|-----------|------|-------|

Machine Directive 2006/42/EC

EMC Directive 2004/108/CE

Low Voltage Directive 2006/95/CE

R&TTE Directive 1999/05/EU

VASCO is an electronic device to be connected to other electrical equipment with which it is to form individual units. It must, therefore, that the putting into service of this unit (with all its subsidiary equipments) to be performed by qualified personnel.

The product conforms to the following regulations:

EN 55011 Class A

EN 61000

EN 60146

EN 50178

EN 60204-1

Ing. Marco Nassuato Operation Manager

| NOTE | | |
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