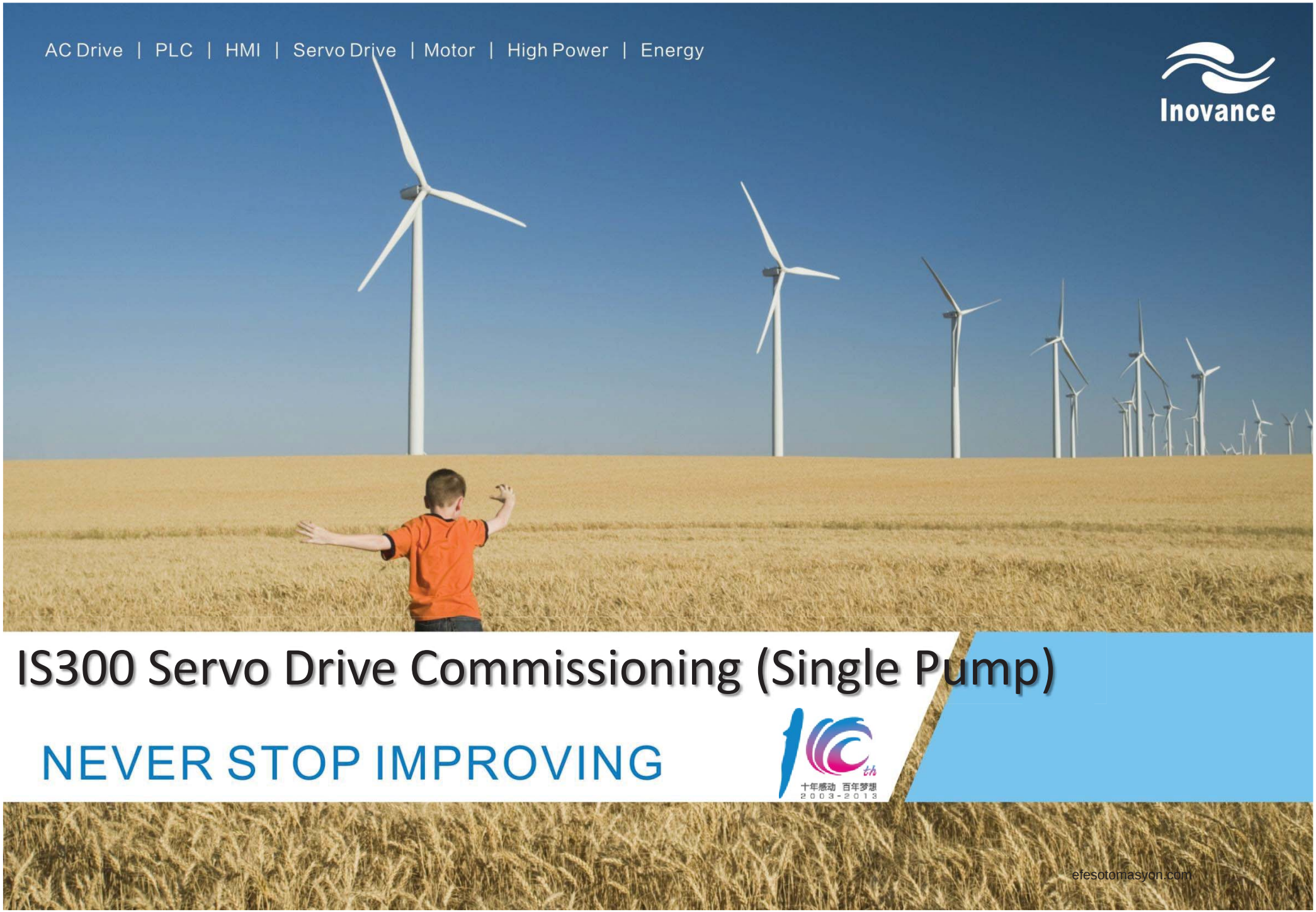

IS300 Servo Drive Commissioning (Single Pump)

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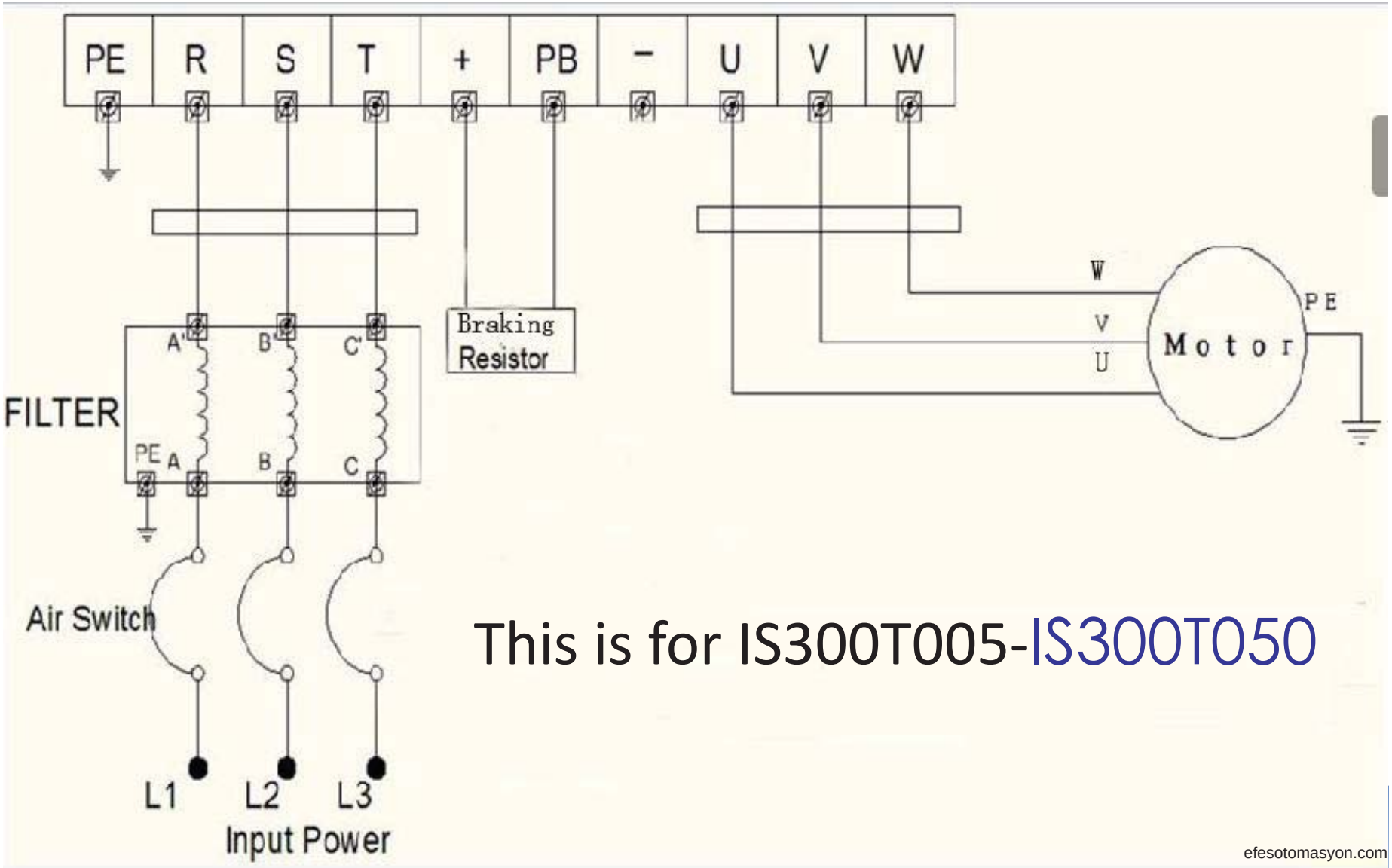
10th 十年感动 百年梦想 2003-2013

Content

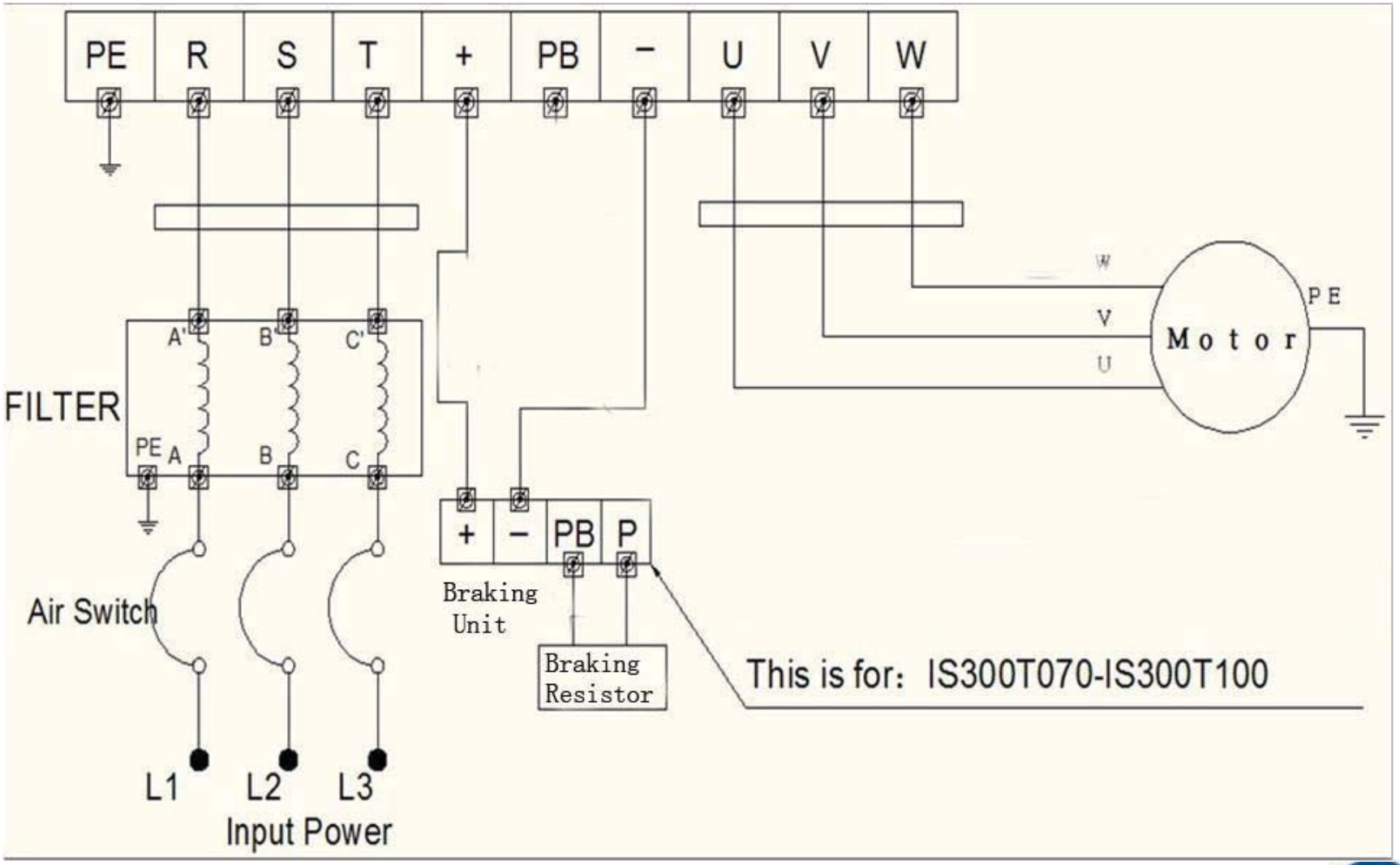
- Wiring
- Commissioning

Main Circuit Wiring diagram

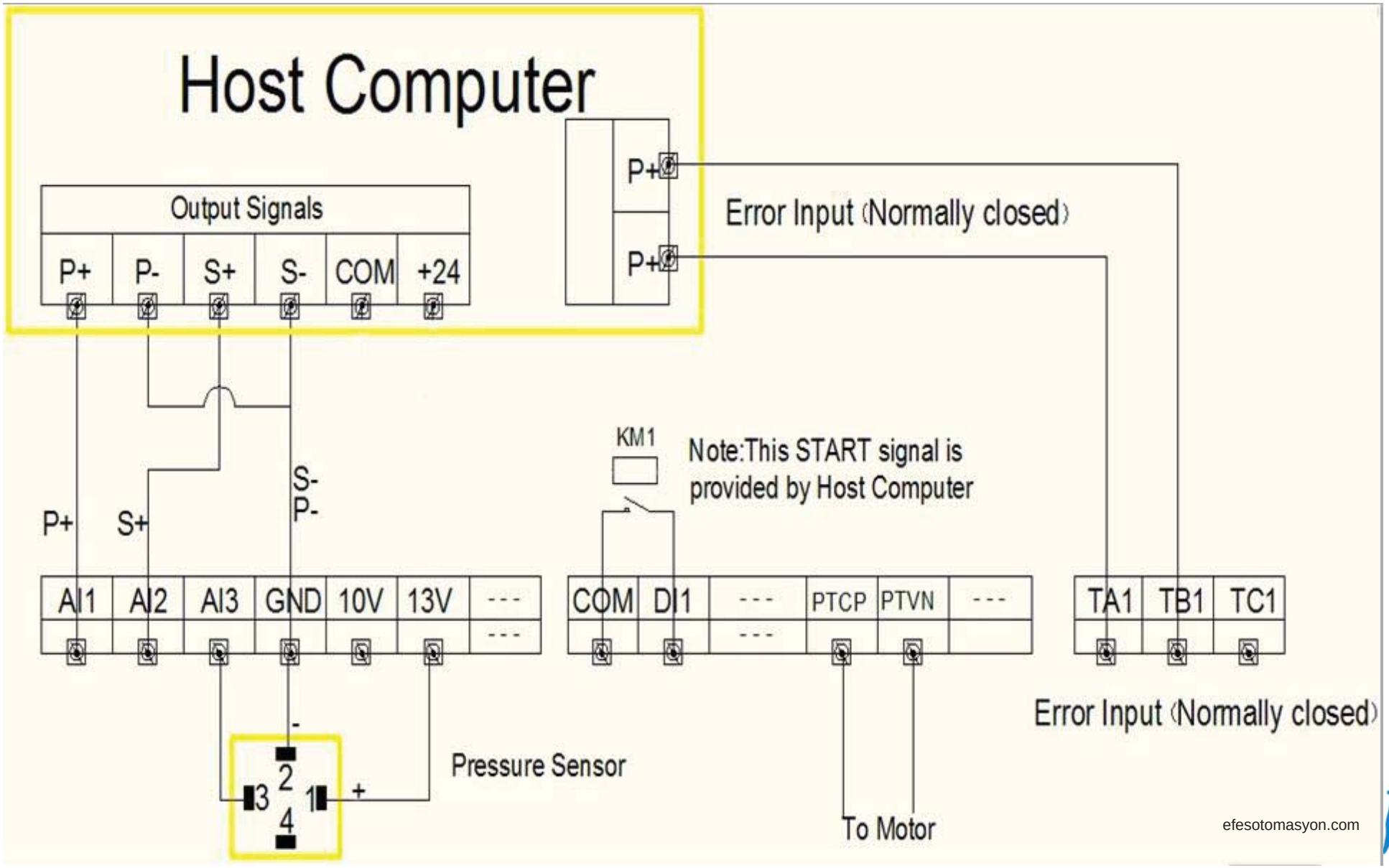


This is for IS300T005-IS300T050

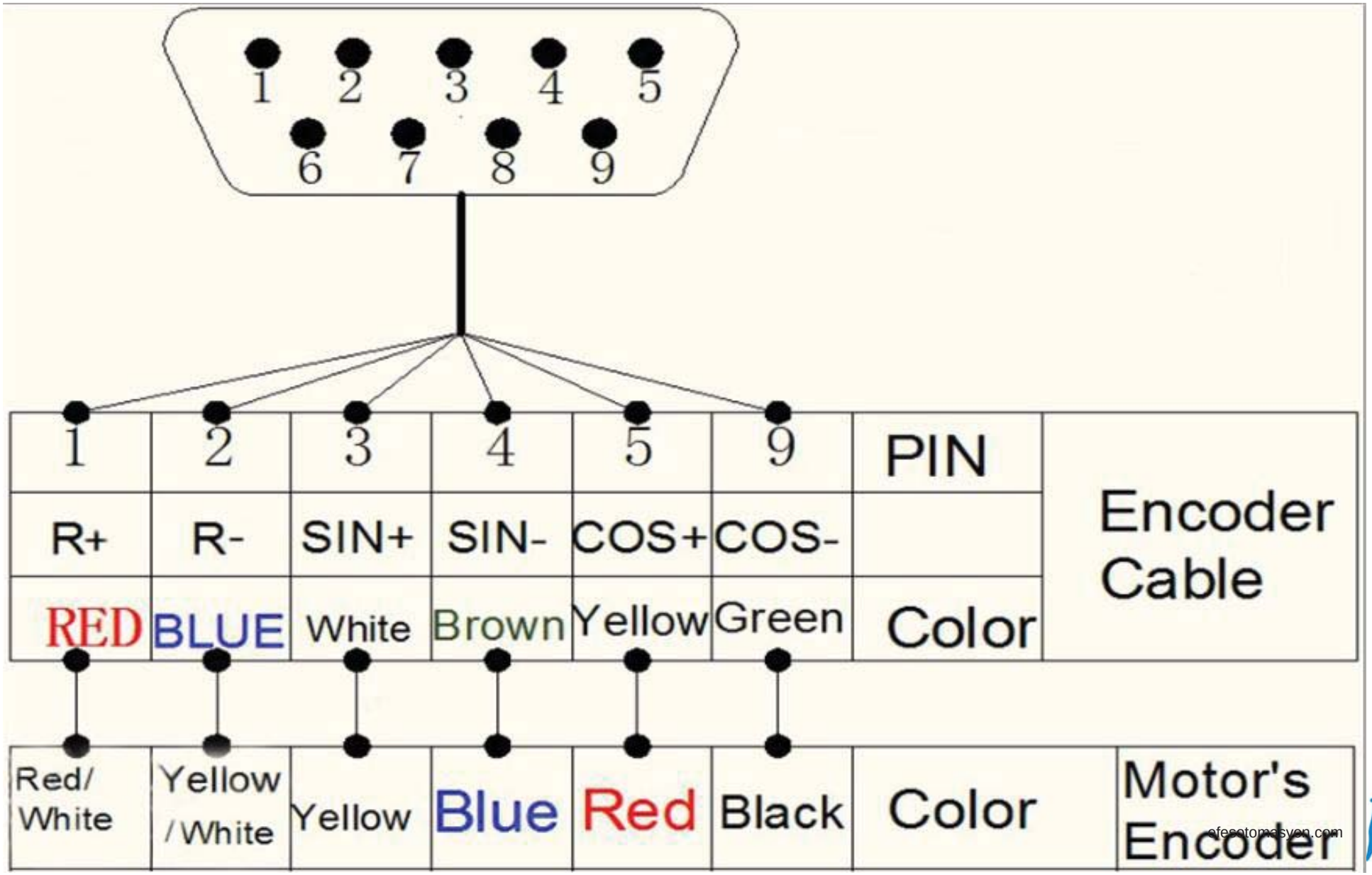
Main Circuit Wiring



Control Circuit Wiring



Encoder Wiring



Commissioning

- ✓ Restore default setting
- ✓ Set control mode & command source
- ✓ Set motor parameter
- ✓ Perform motor auto-tuning
- ✓ Perform trial run to check motor direction
- ✓ Perform AI zero drift correction
- ✓ Set hydraulic control mode & perform fine tuning

Restore default setting

- To restore default setting, simply set FP-01=1

Set control mode & command source

- Set command source: F0-02=0
- Set control mode: A3-00=0

Set motor parameters

Input motor parameters in group F1:

F1-01=Rated motor power

F1-02=Rated motor voltage

F1-03=Rated motor current

F1-04=Rated motor frequency

F1-05=Rated motor rotational speed

- **Note:** Generally, rated frequency of motor cannot be found on its nameplate. You can get the frequency by the following relation between motor's speed and frequency.

Speed (rpm)	1500	1700	2000
Freq. (Hz)	100	113.3	133.3

Perform motor auto-tuning

Static or dynamic auto-tuning?

After changing a new motor: static auto-tuning;

After rectifying a fault: dynamic auto-tuning

- ✓ **Static auto-tuning:**

  Set F1-16=1, and then press “RUN”. The operating panel then displays “TUNE”. When “TUNE” disappears, static auto-tuning is completed.

- ✓ **Dynamic auto-tuning:** (open the relief valve)

  Set F1-16=2, and then press “RUN”. The operating panel then displays “TUNE”. After “TUNE” disappears, check and record the value of A1-02 (Encoder installation angle).

  Set F1-16=2 and then perform auto-tuning again. Then check the value of A1-02.

  Compare the two recorded values of A1-02. Make sure the difference between them is within 5.

Perform trial run to check motor direction

This procedure is required only after replacing a new motor.

Set F0-08=5 (Preset frequency: 5 to 15 Hz suggested), and then press “RUN”.

a) Observe the oil pressure gauge. If pressure is rising up, it indicates that the motor rotates at the right direction.

b) If pressure is not rising up, change any two of the U/V/W cables and perform auto-tuning again.

Perform AI zero drift correction

Set A3-20=1. When “AIcod” is displayed, press “RUN”. The servo drive then performs AI zero drift correction automatically.

- Notes:

✓ AI zero drift correction must be performed after replacing the servo drive, control board or pressure sensor.

✓ If the servo motor automatically rotates in the forward or reverse directly, perform AI zero drift correction first.

✓ If a 0-5V pressure sensor is used, set F4-30=5 (AI3 maximum input).

Set hydraulic control mode

Parameters related to system control mode setting:

1. Maximum rotational speed: A3-01 (speed that corresponds to 100% flow reference)
2. System hydraulic pressure: A3-02
3. Maximum hydraulic pressure: A3-03 (measuring range of the pressure sensor)
4. Minimum flow: A3-09
5. Minimum pressure: A3-10

Set hydraulic control mode & perform fine tuning

Set A3-00=2, and the system enters hydraulic control mode. Plug in DI1 of terminal block CN2, and then tighten up the relief valve. Now you can power on the servo drive.

General setting for fine tuning:

Generally we don't need set the PID parameter , If pressure shocks or overshoot , Try set A3-07=0.035 (Hydraulic pressure control Td1)

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